

# First order DLM & FFBS

The posterior for the parameter  $\theta \in \mathbb{R}^m$  in a 1st order DLM is obtained by at least two alternative ways. The model is

$$y_t | \theta_t \sim N(\theta_t, \sigma^2) \quad \text{conditionally independent } t=1, 2, \dots, n$$

$$t=2, \dots, n \quad \theta_t | \theta_{t-1} \sim N(\theta_{t-1}, \tau^2) \quad \theta_1 | D_0 \sim N(0, \tau^2)$$

## APPROACH 1

$$y = \begin{bmatrix} y_1 \\ \vdots \\ y_n \end{bmatrix} \quad \theta = \begin{bmatrix} \theta_1 \\ \vdots \\ \theta_n \end{bmatrix} \quad y | \theta \sim N(0, \sigma^2 I_m)$$

$$\theta \sim N(0, \tau^2 \Omega_m)$$

where  $(\Omega_m)_{ij} = \begin{cases} i & j \geq i \\ j & j < i \end{cases} \Rightarrow (\Omega_m^{-1})_{ij} = \begin{cases} 2 & i=j \\ -1 & |i-j|=1 \\ 0 & \text{otherwise} \end{cases}$

$$\Rightarrow p(\theta | y) \propto \exp\left\{-\frac{1}{2} \frac{\theta^T \Omega_m^{-1} \theta}{\tau^2}\right\} \exp\left\{-\frac{1}{2} \left(\frac{\theta^T \theta}{\sigma^2} - 2\frac{\theta^T y}{\sigma^2}\right)\right\}$$

$$\Rightarrow (\theta | y) \sim N\left[\left(\frac{\Omega_m^{-1}}{\tau^2} + \frac{I_n}{\sigma^2}\right)^{-1} y; \left(\frac{\Omega_m^{-1}}{\tau^2} + \frac{I_n}{\sigma^2}\right)^{-1}\right]$$

## APPROACH 2

 Forward filtering backward sampling

For  $\theta_0 | D_0 \sim N(m_0, C_0) \Rightarrow t=1, \dots, n \quad (\theta_{t-1} | D_{t-1}) \sim N(m_{t-1}, C_{t-1})$

$$(\theta_t | D_t) \sim N(m_t, C_t)$$

For  $t=n-1, n-2, \dots, 3, 2, 1$

$$m_t = (1 - A_t) m_{t+1} + A_t y_t$$

$$C_t = A_t \sigma^2 + \frac{A_t (C_{t+1} + \tau^2)}{(C_{t+1} + \tau^2 + \sigma^2)}$$

$$\theta_t | D_n \sim N(m_t^m, C_t^m)$$

$$m_t^m = (1 - B_t) m_t + B_t m_{t+1}^m$$

$$C_t^m = (1 - B_t) C_t + B_t C_{t+1}^m$$

with  $m_M^m = m_M$   
 $C_M^m = C_M$