Instructor: Hedibert Freitas Lopes Course: STP 598 Advanced Bayesian Statistical Learning (Class # 31199) Semester: Spring 2022 Due date: 1:30pm, March 21st, 2022.

## Posterior inference via Gibbs sampler

Here is the data (n = 50 observations)

y = c(-2.991, -2.845, -2.640, -1.962, -1.646, -1.627, -1.185, -0.997, -0.917, -0.726, -0.630, -0.382, -0.335, -0.300, -0.216, -0.178, -0.136, -0.013, 0.185, 0.255, 0.367, 0.422, 0.440, 0.447, 0.454, 0.539, 0.558, 0.568, 0.587, 0.696, 0.716, 0.832, 0.861, 0.869, 0.898, 1.012, 1.073, 1.081, 1.112, 1.159, 1.332, 1.342, 1.402, 1.560, 1.728, 1.785, 2.364, 2.491, 2.558, 3.575)

Let us model the data as Student's t with known  $\nu$  degrees of freedom, but unknown location,  $\mu$ , and unknown scale,  $\sigma^2$ . More precisely,

$$y_i | \mu, \sigma^2 \sim t_\nu(\mu, \sigma^2),$$

for i = 1, ..., n. Also, let us assume that  $\mu$  and  $\sigma^2$  are, a priori, independent,

$$\mu \sim N(m_0, C_0)$$
 and  $\sigma^2 \sim IG(a_0, b_0)$ ,

for known hyperparameters  $(m_0, C_0, a_0, b_0)$ . Assume that data =  $\{y_1, \ldots, y_n\}$ .

Scale mixture of Gaussians. The Student's t likelihood is not easy to handle, but there is an important probability result that links the Student's  $t_{\nu}$  with the Gaussian and the inverse-gamma distributions. More precisely, the Student's t is a scale mixture of Gaussian distributions:

If 
$$y_i | \lambda_i, \mu, \sigma^2 \sim N(\mu, \lambda_i \sigma^2)$$
 and  $\lambda_i \sim IG(\nu/2, \nu/2)$ 

then  $y_i|\mu, \sigma^2 \sim t_{\nu}(\mu, \sigma^2)$ . This result allows us to reinterpret the model hierarchically:

$$y_i | \lambda_i \sim N(\mu, \lambda_i \sigma^2), \quad i = 1, \dots, n$$
  
$$\lambda_i \sim IG(\nu/2, \nu/2), \quad i = 1, \dots, n$$
  
$$(\mu, \sigma^2) \sim N(m_0, C_0) IG(a_0, b_0).$$

The (Monte Carlo) price one pays is in the additional parameters,  $(\mu, \sigma^2, \lambda)$ , where  $\lambda = (\lambda_1, \ldots, \lambda_n)$ .

1. Let  $z|\omega \sim N(0,\omega)$  and  $\omega|\nu \sim IG(\nu/2,\nu/2)$ , for  $\nu > 0$ . Show that  $z|\nu \sim t_{\nu}(0,1)$ . Hint:  $p(z|\nu) = \int_0^\infty p(z|\omega)p(\omega|\nu)d\omega$ .

- 2. Derive the full conditional of  $\mu$ , i.e.  $p(\mu | \text{data}, \sigma^2, \lambda)$
- 3. Derive the full conditional of  $\sigma^2$ , i.e.  $p(\sigma^2 | \text{data}, \mu, \lambda)$
- 4. Derive the full conditional of  $\lambda_i$ , i.e.  $p(\lambda_i | \text{data}, \mu, \sigma^2, \lambda_{-i})$ , for i = 1, ..., n and  $\lambda_{-i}$  is  $\lambda$  without the  $\lambda_i$ .
- 5. For  $\nu = 5$  and hyperparameters  $m_0 = 0$ ,  $C_0 = 1$ ,  $a_0 = 5$  and  $b_0 = 1$ , perform posterior inference for  $(\mu, \sigma^2)$ , based on a Gibbs sampler that cycles through the above n + 2 full conditionals. Report your code/implementation and your posterior summaries and findings.
- 6. Let us incorporate  $\nu$  into the analysis with the following discrete prior

$$Pr(\nu) \propto \nu e^{-0.1\nu}$$
  $\nu = 1, 2, \dots, 100.$ 

Derive its full conditional distribution  $Pr(\nu | \text{data}, \mu, \sigma^2)$  (easy, since it is a discrete distribution), and revisit question 5 above.

- 7. Simulate yourself n = 50 from the standard Gaussian. Assuming the previous modeling structure (prior and likelihood), plot the posterior distribution of  $\nu$ . Does it concentrate on large values of  $\nu$ , which would indiate approximate Gaussian behavior? Comment your findings.
- 8. What would change in your Gibbs sampler if  $\mu$ , the location parameter, is replaced by a linear preditor

$$\beta_0 + \beta_1 x_{i1} + \dots + x_{iq}$$

for known and q fixed predictors  $x_{ij}$ , for  $i = 1, \ldots, n$  and  $j = 1, \ldots, q$ , and prior

$$\beta = (\beta_0, \beta_1, \dots, \beta_q) \sim N_q(m_0, V_0),$$

for known hyperparameters  $b_0$ , a q-dimensional vector and  $B_0$ , a  $q \times q$  covariance matrix?